

5.9 Problems

Problem 1. Use the Runge-Kutta method for systems to approximate the solutions of the following system of first-order differential equations and compare the results to the actual solutions.

$u_1' = -4u_1 - 2u_2 + \cos(t) + 4\sin(t)$, $u_2' = 3u_1 + u_2 - 3\sin(t)$, $u_1(0) = 0$, $u_2(0) = -1$, $0 \leq t \leq 2$, $h = .1$.
Actual solutions $u_1(t) = 2e^{-t} - 2e^{-2t} + \sin(t)$ and $u_2(t) = -3e^{-t} + 2e^{-2t}$

$$\begin{pmatrix} u_1(t) \\ u_2(t) \end{pmatrix}' = \begin{pmatrix} -4 & -2 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} u_1(t) \\ u_2(t) \end{pmatrix} + \begin{pmatrix} \cos(t) + 4\sin(t) \\ -3\sin(t) \end{pmatrix} \quad \begin{pmatrix} u_1(0) \\ u_2(0) \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

~~etc~~

5.10 Problems

Problem 2. Show that if the initial value problem $y' = f(t, y)$, $a \leq t \leq b$, $y(a) = \alpha$ is approximated by a one-step difference method: $w_0 = \alpha$, $w_{i+1} = w_i + h\varphi(t_i, w_i, h)$. And there exists $h_0 > 0$ and $\varphi(t, w, h)$ continuous and Lipschitz in the w variable with Lipschitz constant L on

$$D = \{(t, w, h) | a \leq t \leq b, -\infty < w < \infty, 0 \leq h \leq h_0\}$$

then there exists a constant $K > 0$ such that

$$|u_i - v_i| \leq K|u_0 - v_0|$$

for each $1 \leq i \leq N$ whenever $\{u_i\}_{i=1}^N$ and $\{v_i\}_{i=1}^N$ satisfy the difference equation $w_{i+1} = w_i + h\varphi(t_i, w_i, h)$

$$\begin{aligned} |u_1 - v_1| &= |u_0 + h\varphi(t_0, u_0, h) - v_0 - h\varphi(t_0, v_0, h)| \\ &\leq |u_0 - v_0| + h |\varphi(t_0, u_0, h) - \varphi(t_0, v_0, h)| \\ &\leq |u_0 - v_0| + hL|u_0 - v_0| \\ &\leq |u_0 - v_0| (1 + hL) \end{aligned}$$

$$|u_2 - v_2| \leq \dots \leq |u_1 - v_1| (1 + hL) \leq |u_0 - v_0| (1 + hL)^2$$

By induction

$$|u_N - v_N| \leq |u_0 - v_0| (1 + hL)^N$$

$$\Rightarrow \forall j=1, \dots, N$$

$$|u_j - v_j| \leq |u_0 - v_0| \underbrace{(1 + hL)^j}_K$$

$$\lim_{N \rightarrow \infty} \left(1 + \frac{2L(b-a)}{N}\right)^N = e^{2L(b-a)}$$

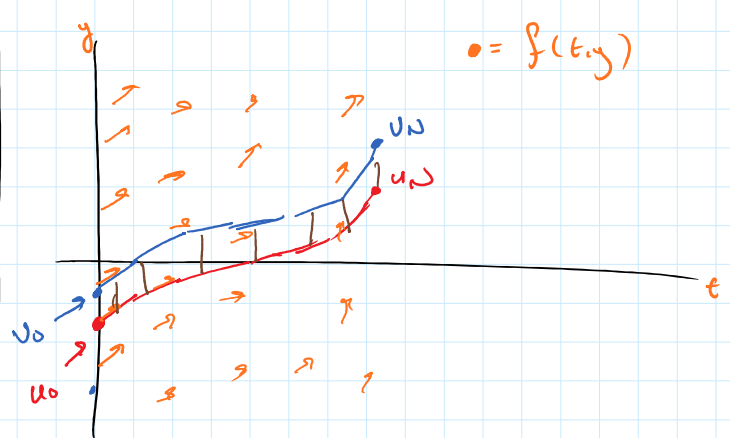
32. The Runge-Kutta method of order four can be written in the form

$$\begin{aligned} w_0 &= \alpha, \\ w_{i+1} &= w_i + \frac{h}{6} f(t_i, w_i) + \frac{h}{3} f(t_i + \alpha_1 h, w_i + \delta_1 h f(t_i, w_i)) \\ &\quad + \frac{h}{3} f(t_i + \alpha_2 h, w_i + \delta_2 h f(t_i + \gamma_2 h, w_i + \gamma_3 h f(t_i, w_i))) \\ &\quad + \frac{h}{6} f(t_i + \alpha_3 h, w_i + \delta_3 h f(t_i + \gamma_4 h, w_i + \gamma_5 h f(t_i + \gamma_6 h, w_i + \gamma_7 h f(t_i, w_i)))) \end{aligned}$$

Find the values of the constants

$\alpha_1, \alpha_2, \alpha_3, \delta_1, \delta_2, \delta_3, \gamma_2, \gamma_3, \gamma_4, \gamma_5, \gamma_6,$ and γ_7 .

What does this mean?

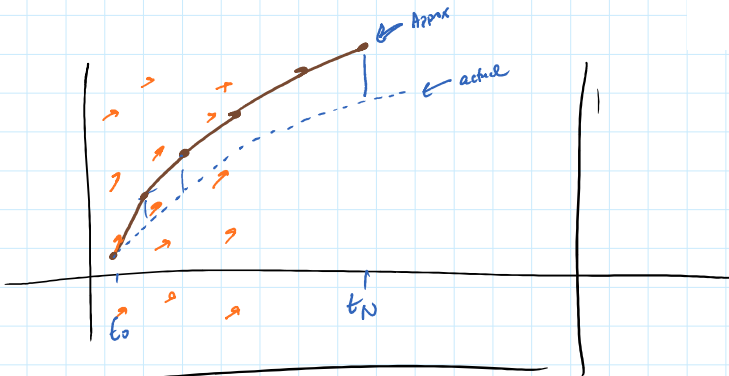


Problem 4. Given the multistep method

$$w_{i+1} = -\frac{3}{2}w_i + 3w_{i-1} - \frac{1}{2}w_{i-2} + 3hf(t_i, w_i)$$

for $i = 2, \dots, N-1$, with starting values w_0, w_1, w_2 . (a) Find the local truncation error. (b) comment on consistency, stability, and convergence.

Problem 3. Show that Runge-Kutta method of order four is consistent using the results of exercise 32 in section 5.4.



$$y_{i+1} - w_{i+1}$$

Computed assuming correct at $i=1$

$$y'(t) = f(t, y(t))$$

$$y_i = \underline{\underline{\text{actual solution at } t_i}}$$

d) $\tau_{in}(h) = \text{"Local truncation error"} = \frac{y_{i+1} - (-\frac{3}{2}y_i + 3y_{i-1} - \frac{1}{2}y_{i-2})}{h} - 3f(t_i, y_i)$

$|\tau_{in}(h)|$

$$y(t_{i+h}) + \frac{3}{2}y(t_i) - 3y(t_{i-1}) - \frac{1}{2}y(t_{i-2}) - 3f(t_i, y(t_i))$$

Let $P(t)$ be a 3rd order poly interpolating $y(t)$ at $t_{i-2}, t_{i-1}, t_i, t_{i+1}$

$$y(t) = P(t) + \frac{y^{(4)}(\xi(t))}{24} (t-t_{i-2})(t-t_{i-1})(t-t_i)(t-t_{i+1})$$

$$\frac{P(t_{i+h}) + \frac{3}{2}P(t_i) - 3P(t_{i-1}) - \frac{1}{2}P(t_{i-2})}{h} \rightarrow f(t_i, y(t_i))$$

$$f(t_i, y(t_i)) = \frac{d}{dt} y(t_i) = \frac{d}{dt} \left(P(t) + \frac{y^{(4)}(\xi(t))}{24} (t-t_{i-2})(t-t_{i-1})(t-t_i)(t-t_{i+1}) \right)$$

$$= P'(t_i) + \frac{y^{(4)}(\xi(t_i)) (2h)(h)(-h)}{24} = \frac{P'(t_i)}{4} + \frac{h^3 y^{(4)}(\xi(t_i))}{12} \quad t = t_i$$

$$= \frac{P(t_{i+h}) + \frac{3}{2}P(t_i) - 3P(t_{i-1}) - \frac{1}{2}P(t_{i-2})}{h} - 3P'(t_i) + \frac{h^3 y^{(4)}(\xi(t_i))}{4} = \tau$$

$= 0$

$$P = a + bt + ct^2 + dt^3$$